#### Multi-method Modelling and Simulation and Co-Simulation - Development, Trends and Education

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#### **ARGESIM BENCHMARKS IN SNE**

C1 Lithium-Cluster Dynamics, SNE 0(1), 1990 C2 Flexible Assembly System, SNE 1(1), 1991 C3 Generalized Class-E Amplifier, SNE 1(2), 1991 C4 Dining Philosophers I, SNE 1(3), 1991 C5 Two State Model, SNE 2(1), 1992 C6 Emergency Department SNE 2(3), 1992 C7 Constrained Pendulum, SNE 3(1), 1993 CP1 Parallel Simulation Techniques, SNE 4(1), 1994 C8 Canal-and-Lock System, SNE 6(1), 1996 C9 Fuzzy Control of a Two Tank System, SNE 6(2), 1996 C10 Dining Philosophers II, SNE 6(3), 1996 C11 SCARA Robot, SNE 8(1), 1998



COMPARISON 11: SCARA ROBO

EUROSIM'98 CONGRESS

A EUROPEAN FORUM ON SIMULATION ACTIVITIES

March 1998

**FION NEWS** 

Number 22

**Mathematical** 

Comparison of Simulation Software ....  $\rightarrow$ 

ASC TU VIENNA Mathematical Modelling and Simulation

#### **ARGESIM BENCHMARKS IN SNE**

C12 Collision of Spheres, SNE 9(3), 1999 C13 Crane Crab and Embedded Control, SNE 11(1), 2001 C14 Supply Chain, SNE 11(2-3), 2001 C15 Clearance Identification, SNE 12(2-3), 2002 C16 Restaurant Business Dynamics, SNE 14(1), 2004 C17 Spatial Dynamics of SIR Epidemics, SNE 14(2-3), 2004; C18 Neural Networks vs. Transfer Functions, SNE 15(1), 2005 C19 Pollution in Groundwater Flow, SNE 15(2-3), 2005 CP2 Parallel & Distributed Simulation, SNE 16(2), 2006



. → Benchmarks for Modelling Approaches and Simulation Implementations



#### **ARGESIM BENCHMARKS IN SNE**

C17 Spatial Dynamics of SIR Epidemics, rev. SNE 25(2), 2015 C18 Neural Networks vs. Transfer Functions, SNE 15(1), 2005 C19 Pollution in Groundwater Flow, rev. SNE 16(3-4), 2006 CP2 Parallel & Distributed Simulation, SNE 16(2), 2006 C20 Complex Assembly System, SNE 21(3-4), 2011

- SNE is publishing revised definitions
- Extended solution documentation (> 1 page)
- Extended Benchmarks: SNE introduces extended benchmarks, comparing modelling and simulation
   paradigms, or dealing with more complex models and experiments
- Documentation and publication in SNE of 'solutions' may take more pages – up to 10 pages SNE.







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#### **ARGESIM BENCHMARKS IN SNE**

C17 Spatial Dynamics of SIR Epidemics, rev. SNE 25(2), 2015 C18 Neural Networks vs. Transfer Functions, SNE 15(1), 2005 C19 Pollution in Groundwater Flow, rev. SNE 16(3-4), 2006 CP2 Parallel & Distributed Simulation – CO-Simulation, SNE 16(2), 2006 C20 Complex Assembly System, SNE 21(3-4), 2011

#### C21 State Events and Structural-dynamic Systems, SNE 26(2), 2016

Benchmarks for Modelling Approaches and Simulation Implementations C22 Multimethod Modelling and Simulation, SNE 27, 2017





#### **DEVELOPMENT OF SYSTEM SIMULATION**

$$\vec{x}(t) = \dot{f}(t, \vec{x}(t), \vec{u}(t)), \qquad \vec{x}(t_0) = x_0, \qquad \mathbf{ODE}$$

### $\dot{\vec{x}}(t) = \vec{f}(t, \vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}), \quad \vec{x}(t_0) = x_0 \quad \text{DAE}$ $\vec{g}(\vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}) = \vec{0}$

$$h^{B}(\vec{x}(t),\vec{u}(t),\vec{p}) \stackrel{!\pm}{=} \vec{0} \stackrel{\hat{t}^{B}}{\Rightarrow} E^{B}\left(\vec{x}\left(\hat{t}^{B}\right),\vec{u}\left(\hat{t}^{B}\right),\vec{p}\right)$$
...
**State Events**



#### **DEVELOPMENT OF SYSTEM SIMULATION**

$$\dot{\vec{x}}(t) = \vec{f}(t, \vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}), \quad \vec{x}(t_0) = x_0 \quad \mathsf{DAE}$$

$$\vec{g}(\vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}) = \vec{0} \quad \mathsf{State Events}$$

$$h^B(\vec{x}(t), \vec{u}(t), \vec{p}) \stackrel{! \pm}{=} \vec{0} \stackrel{\hat{t}^B}{\Rightarrow} E^B\left(\vec{x}\left(\hat{t}^B\right), \vec{u}\left(\hat{t}^B\right), \vec{p}\right)$$

- Parameter change event SE-P
- Input change event SE-I
- State change event SE-X
- Function change event SE-F
- Structure change event SE-S
- Output trace event SE-O
- Algorithm event SE-A

#### Event function Event action



#### **DEVELOPMENT OF SYSTEM SIMULATION**

$$\dot{\vec{x}}(t) = \vec{f}(t, \vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}), \quad \vec{x}(t_0) = x_0 \quad \text{DAE}$$

$$\vec{g}(\vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}) = \vec{0} \quad \text{State Events}$$

$$l \pm \vec{t}^B = \vec{0} \Rightarrow E^B \left(\vec{x}\left(\hat{t}^B\right), \vec{u}\left(\hat{t}^B\right), \vec{p}\right) \quad \text{Event function}$$

$$F_{\text{vent action}}$$



#### Physical Modelling – State Space ,unknown'



#### **STATE EVENT HANDLING**

$$\dot{\vec{x}}(t) = \vec{f}(t, \vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}), \quad \vec{x}(t_0) = x_0$$
  

$$\vec{g}(\vec{x}(t), \vec{z}(t), \vec{u}(t), \vec{p}) = \vec{0} \quad \text{DAE}$$
  

$$h^B(\vec{x}(t), \vec{u}(t), \vec{p}) \stackrel{!\pm}{=} \vec{0} \stackrel{\hat{t}^B}{\Rightarrow} E^B\left(\vec{x}\left(\hat{t}^B\right), \vec{u}\left(\hat{t}^B\right), \vec{p}\right) \quad \text{State Events}$$
  
...

- Parameter change event SE-P
- Input change event SE-I
- State change event SE-X
- Function change event SE-F
- Structure change event SE-S
- Output trace event SE-O
- Algorithm event SE-A

#### Structural-dynamic Systems

#### **Structural-dynamic Systems**

$$h^{B}(\vec{x}(t),\vec{u}(t),\vec{p}) \stackrel{!\pm}{=} \vec{0} \stackrel{\hat{t}^{B}}{\Rightarrow} E^{B}\left(\vec{x}\left(\hat{t}^{B}\right),\vec{u}\left(\hat{t}^{B}\right),\vec{p}\right)$$

- Parameter change event –
- Input change event
- State change event
- Function change event
- Structure change event
- Output trace event
- Algorithm event



- 1. Detection of the event
- 2. Localisation of event
- 3. Event Action
- 4. Restart of solver

*Detection* of the event

Localisation of event

Event Action

Restart of solver

#### **Structural-dynamic Systems**

$$h^{B}(\vec{x}(t),\vec{u}(t),\vec{p}) \stackrel{!\pm}{=} \vec{0} \stackrel{\hat{t}^{B}}{\Rightarrow} E^{B}\left(\vec{x}\left(\hat{t}^{B}\right),\vec{u}\left(\hat{t}^{B}\right),\vec{p}\right)$$

- Parameter change event –
- Input change event
- State change event
- Function change event
- Structure change event
- Output trace event
- Algorithm event

Model Internal State Events: I-SE-P I-SE-S

I-SE-D



1.

2

3.

4.











#### Charact. Functions Static Mod





#### Charact. Functions Static Mod









System Dynamics Modelica Bond Graphs Agent-based Petri Nets CA Mod State Automata

**Transfer Functions** 

Charact. Functions Static Mod











DAEs Diff Eq. PDEs

Event Mod DEVS Process Mod Agent-based



Transfer Functions System Dynamics Modelica Bond Graphs Agent-based Petri Nets CA Mod State Automata



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#### **Multimethod Modelling**







System Dynamics Modelica Bond Graphs Agent-based Petri Nets CA Mod State Automata

**Transfer Functions** 







**System Dynamics** Modelica **Bond Graphs** Agent-based Petri Nets CA Mod

Charact. Functions Static Mod

**Consequences for Edu in ModSim ?** 





Transfer Functions System Dynamics Modelica Bond Graphs Agent-based Petri Nets CA Mod

Charact. Functions Static Mod

#### State Automata Consequences for Edu in ModSim ? Challenge



DAEs Diff Eq. **PDEs** 

Event Mod DEVS Process Mod Agent-based



**Transfer Functions** System Dynamics Modelica **Bond Graphs** Agent-based Petri Nets CA Mod State Automata

Charact, Functions Static Mod

#### **Consequences for Edu in ModSim ?** Challenge -Interdisciplinary Edu in ModSim

F. Breitenecker, A. Körner, N. Popper Kickoff CEEPUS Network: CIII-BG-1103-01-1617 Modelling, Simulation and Computer-aided Design in Engineering and Management, Sofia, Oct. 2016



DAEs Diff Eq. PDEs

Event Mod DEVS Process Mod Agent-based



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#### Consequences for Edu in ModSim ? Challenge

## -Interdisciplinary Edu in ModSim -Basic Method Edu in ModSim -Basic Tool Edu in ModSim



DAEs Diff Eq. PDEs

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#### Consequences for Edu in ModSim ? Challenge



DAEs Diff Eq. PDEs

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### Consequences for Edu in ModSim ?ChallengePossible Solutions

-Interdisciplinary Edu in ModSim

- -Basic Method Edu in ModSim
- -Basic Tool Edu in ModSim

-Specialisation Edu in ModSim



DAEs Diff Eq. PDEs

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### Consequences for Edu in ModSim ?ChallengePossible Solutions

-Interdisciplinary Edu in ModSim In existing or new curricula -Basic Method Edu in ModSim -Basic Tool Edu in ModSim -Specialisation Edu in ModSim



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-Interdisciplinary Edu in ModSim In existing or new curricula -Basic Method Edu in ModSim -Basic Tool Edu in ModSim -Specialisation Edu in ModSim



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### Consequences for Edu in ModSim ?ChallengePossible Solutions



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### Consequences for Edu in ModSim ?ChallengePossible Solutions

-Interdisciplinary Edu in ModSim In existing or new curricula -Basic Method Edu in ModSim -Basic Tool Edu in ModSim -Specialisation Edu in ModSim Lecture Exchange - EL,DL

